Computation of Richelot isogeny chains

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Genus-2 curves and their Jacobians

A genus-2 curve C over a field K with $char(K) \neq 2$ is a curve defined by an equation of the form

$$\mathcal{C}: y^2 = f(x),$$

where $f \in K[x]$ is a square-free polynomial of degree 5 or 6. We call $y^2 = f(x)$ a hyperelliptic equation for C.

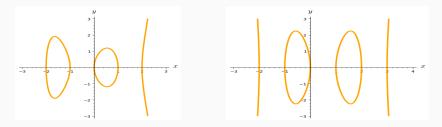


Figure 1: $y^2 = x(x^2 - 1)(x^2 - 4)$

Figure 2:
$$y^2 = x(x^2 - 1)(x^2 - 4)(x - 3)$$

Hyperelliptic Equations

• A coordinate transformation

$$t: x \mapsto x' = \frac{ax+b}{cx+d}, \ y \mapsto y' = \frac{ey}{(cx+d)^3}$$

with $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in GL(K), \ e \in K \setminus \{0\}$ allows to move between different hyperelliptic equations.

We introduce two types of hyperelliptic equations:

Type 1:
$$y^2 = E x(x^2 - Ax + 1)(x^2 - Bx + C)$$

Type 2: $y^2 = (x^2 - 1)(x^2 - A)(Ex^2 - Bx + C)$
with coefficients $A, B, C, E \in K$.

➤ The existence of Type-1 and Type-2 equations over K is equivalent.
 ➤ For C : y² = f(x) over a finite field K: If f splits over K, then C admits equations of Type 1 and 2.

Points of genus-2 curves

The set of points of a hyperelliptic curve $C: y^2 = f(x)$ is given by

$$\mathcal{C}(\bar{K}) = \{(u,v) \in \bar{K}^2 \mid v^2 = f(u)\} \cup \begin{cases} \{\infty\} & \text{if } \deg(f) = 5\\ \{\infty_+, \infty_-\} & \text{if } \deg(f) = 6 \end{cases}$$
affine points point(s) at infinity

The Weierstrass points of C are the points fixed by the hyperelliptic involution τ , defined as $\tau(u, v) = (u, -v)$ and $\tau(\infty_{\pm}) = \infty_{\mp}$, resp. $\tau(\infty) = \infty$.

• Every genus-2 curve has precisely 6 Weierstrass points.



1 In contrast to elliptic curves, the set $C(\bar{K})$ is **not** a group.

The Jacobian of a genus-2 curve

We write $\mathcal{J}(\mathcal{C})$ for the **Jacobian variety** of a genus-2 curve.

- It is a a principally polarized abelian variety of dimension 2.
- As groups: $\mathcal{J}(\mathcal{C})(L) = Pic^0_{\mathcal{C}}(L)$ for any field extension L/K.
- Any $R \in \mathcal{J}(\mathcal{C})$ has a unique presentation $R = [P_1 + P_2 D_{\infty}]$, where $P_1, P_2 \in \mathcal{C}(\bar{K})$ with $\tau(P_1) \neq \tau(P_2)$ and $D_{\infty} = \begin{cases} 2 \cdot \infty & \text{if } \deg(f) = 5, \\ \infty_+ + \infty_- & \text{if } \deg(f) = 6. \end{cases}$

Mumford presentation

$$\begin{split} R &= J(a,b) \\ \text{For } P_1 &= (u_1,v_1), P_2 = (u_2,v_2), \\ \text{define } a &= (x-u_1)(x-u_2) \text{ and } \\ b &= b_1x + b_0 \text{ so that } b(u_1) = v_1 \\ \text{and } b(u_2) &= v_2. \end{split}$$

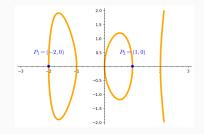


Figure 3: Element $J(x^2 + x - 2, 0)$

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Isogenies of Jacobians of genus-2 curves

Torsion elements

Consider $\mathcal{C}: y^2 = f(x)$ over a finite field K with char(K) = p.

- $\mathcal{J}(\mathcal{C})[m] \cong (\mathbb{Z}/m\mathbb{Z})^4$ for $m \in \mathbb{N}$ with $p \nmid m$.
- The Weil pairing

$$e_m: \mathcal{J}(\mathcal{C})[m] \times \mathcal{J}(\mathcal{C})[m] \to \boldsymbol{\mu}_m.$$

is a bilinear, alternating pairing.

Example:
$$m = 2$$
, $f = \prod_{i=1}^{6} (x - r_i)$

J(C)[2] \ {0} = {J((x - r_i)(x - r_j), 0) | i ≠ j}.
 ⇒ Correspondence between pairs of Weierstrass points of C and 2-torsion elements of J(C).

•
$$e_2 \left(J \left((x - r_i)(x - r_j), 0 \right), J \left((x - r_k)(x - r_l), 0 \right) \right)$$

=
$$\begin{cases} -1 & \text{if } |\{i, j\} \cap \{k, l\}| = 1, \\ 1 & \text{otherwise.} \end{cases}$$

Consider $\mathcal{J}(\mathcal{C})$ over K with char(K) = p and let $\ell \neq p$ prime.

- An (ℓ, ℓ)-isogeny is an isogeny φ : J(C) → A = J(C)/G, ¹ where G ≃ (ℤ/ℓℤ)² and e_{ℓ|G} ≡ id.
 ⇒ G is called maximal ℓ-isotropic.
- Non-backtracking composition of (ℓ, ℓ) -isogenies:

$$\mathcal{J}(\mathcal{C}) \to \mathcal{A}_1 \to \cdots \to \mathcal{A}_n.$$

For $G = \ker(\mathcal{J}(\mathcal{C}) \to \mathcal{A}_n)$, we have that $e_{\ell^n|_G} = id$ and $G \cong \mathbb{Z}/\ell^n \mathbb{Z} \times \mathbb{Z}/\ell^{n-k} \mathbb{Z} \times \mathbb{Z}/\ell^k \mathbb{Z}$ for some $0 \le k \le n/2$. $\Rightarrow G$ is called maximal ℓ^n -isotropic.

 An (ℓⁿ, ℓⁿ)-isogeny is an isogeny as above, where k = 0, i.e. G ≅ (ℤ/ℓⁿℤ)².

 $^{^1}$ In general, ${\cal A}$ is a principally polarized abelian surface. In most cases this is again the Jacobian of a genus-2 curve ${\cal C}'.$

Richelot Isogenies

Let $C: y^2 = g_1(x)g_2(x)g_3(x)$ with $g_i = g_{2,i}x^2 + g_{1,i}x + g_{0,i}$ and write $\delta = \det((g_{i,j})_{i,j})$.

- The group $G = \langle J(g_1, 0), J(g_2, 0) \rangle = \{0, J(g_1, 0), J(g_2, 0), J(g_3, 0)\}$ is maximal 2-isotropic.
- If $\delta \neq 0,$ then $\mathcal{J}(\mathcal{C})/G = \mathcal{J}(\mathcal{C}'),$ where

$$\mathcal{C}': y^2 = h_1(x)h_2(x)h_3(x) \quad \text{with } h_i = \delta^{-1}(g'_{i+1}g_{i+2} - g_{i+1}g'_{i+2}).$$

• The isogeny $\phi: \mathcal{J}(\mathcal{C}) \to \mathcal{J}(\mathcal{C}')$ is called **Richelot isogeny** and it is defined by the correspondence

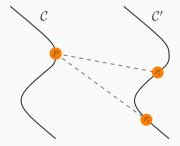
$$\mathcal{R}: \quad 0 = g_1(u)h_1(u') + g_2(u)h_2(u')$$
$$vv' = g_1(u)h_1(u')(u-u')$$

for points $(P,P')=((u,v),(u',v'))\in \mathcal{C}\times \mathcal{C}'.$

Richelot correspondence

Recall $\mathcal{R} \subset \mathcal{C} \times \mathcal{C}'$.

$$\mathcal{R}: \quad 0 = g_1(u)h_1(u') + g_2(u)h_2(u')$$
$$vv' = g_1(u)h_1(u')(u-u').$$



The correspondence induces a map $\mathcal{J}(\mathcal{C}) \to \mathcal{J}(\mathcal{C}')$:

$$[P+Q-D_{\infty}]\mapsto\underbrace{[P_1+P_2+Q_1+Q_2-2D'_{\infty}]}_{\text{unreduced representation}}=[P'+Q'-D'_{\infty}].$$

Richelot Isogeny Chains

Setup: A genus-2 curve

$$\mathcal{C}: y^2 = (x^2 - 1)(x^2 - A)(Ex^2 - Bx + C)$$

and a (special) symplectic basis (B_1, B_2, B_3, B_4) for $\mathcal{J}(\mathcal{C})[2^n]$.

Input: $a, b, c \in \mathbb{Z}/2^n\mathbb{Z}$ defining $G = \langle B_1 + aB_3 + bB_4, B_2 + bB_3 + cB_4 \rangle$. Output: $\mathcal{J}(\mathcal{C}') = \mathcal{J}(\mathcal{C})/G$.

Q Restriction in our work: We will only consider isogenies where the codomain is again the Jacobian of a hyperelliptic curve. In general, one could also have $\mathcal{J}(\mathcal{C})/G = \mathcal{E}_1 \times \mathcal{E}_2$ for two elliptic curves $\mathcal{E}_1, \mathcal{E}_2$.

Our Algorithm

Computation of $\mathcal{J}(\mathcal{C})/G$ with $G = \langle J_1, J_2 \rangle \subset \mathcal{J}(\mathcal{C})[2^n]$.

General outline: Composition of n Richelot isogenies

$$\mathcal{J}_0 = \mathcal{J}(\mathcal{C}_0) \xrightarrow{\phi_1} \mathcal{J}_1 = \mathcal{J}(\mathcal{C}_1) \xrightarrow{\phi_2} \mathcal{J}_2 = \mathcal{J}(\mathcal{C}_2) \longrightarrow \dots \xrightarrow{\phi_n} \mathcal{J}_n = \mathcal{J}(\mathcal{C}_n).$$

where $\ker(\phi_i) = \langle 2^{n-i}\psi_{i-1}(J_1), 2^{n-i}\psi_{i-1}(J_2) \rangle.$

Step i:

- transformation to Type-1 equation with special kernel form
- $\hat{\phi}_i$: application of our (2,2)-isogeny formula

$$\mathcal{J}_{i-1} = \mathcal{J}(\mathcal{C}_{i-1}) \xrightarrow{\phi_i} \mathcal{J}_i = \mathcal{J}(\mathcal{C}_i)$$

$$\downarrow^{\hat{\phi}_i}$$

$$\mathcal{J}'_{i-1} = \mathcal{J}(\mathcal{C}'_{i-1})$$

(2,2)-isogeny formula

Theorem (K.) Let $C: y^2 = Ex(x^2 - Ax + 1)(x^2 - Bx + C)$ with $C \neq 1$ and $G = \langle J(x,0), J(x^2 - Ax + 1, 0) \rangle \subset \mathcal{J}(C)[2].$

- Then $\mathcal{J}(\mathcal{C})/G=\mathcal{J}(\mathcal{C}')$ with

$$\mathcal{C}': y^2 = (x^2 - 1)(x^2 - A')(E'x^2 - B'x + C'),$$

where
$$A' = C$$
, $B' = \frac{2}{E}$, $C' = \frac{B - AC}{E(1 - C)}$, $E' = \frac{A - B}{E(1 - C)}$.

• We provide explicit formulas for the (2, 2)-isogeny $\phi : \mathcal{J}(\mathcal{C}) \to \mathcal{J}(\mathcal{C}')$. I.e. expressions $a'_i, b'_i \in K[A, B, C, E, a_0, a_1, a_2, b_0, b_1]$ so that

 $\phi(J(a_2x^2+a_1x+a_0,b_1x+b_0)) = J(a_2'x^2+a_1'x+a_0',b_1'x+b_0') \in \mathcal{J}(\mathcal{C}').$

Transformation

Goal: Given $C: y^2 = f(x)$, a (2, 2)-group $\langle J(g_1, 0), J(g_2, 0) \rangle$ and a $R \in \mathcal{J}(C)$ with $2 \cdot R = J(g_1, 0)$: find a transformation $t: (x, y) \mapsto (x', y')$ so that

•
$$C': y'^2 = Ex'(x'^2 - Ax' + 1)(Ex'^2 - Bx' + C).$$

• $t(g_1) = x'$ and $t(g_2) = {x'}^2 - Ax' + 1.$

Step 1: Factorize $g_1(x) = (x - \alpha_1)(x - \alpha_2)$, $g_2(x) = (x - \beta_1)(x - \beta_2)$ (Note: no square-root computations necessary due to the special setup).

Step 2: Set
$$\hat{t}: x \mapsto \hat{x} = \frac{x - \alpha_2}{x - \alpha_1}, \ y \mapsto \hat{y} = \frac{y}{(x - \alpha_1)^3}$$
 and compute $\hat{\mathcal{C}}: \hat{y}^2 = c_f \cdot \hat{x}(\hat{x} - \hat{\beta}_1)(\hat{x} - \hat{\beta}_2)(\hat{x} - \hat{\gamma}_1)(\hat{x} - \hat{\gamma}_2).$

Step 3: Compute $a \in K$ such that satisfies $a^2 = \frac{1}{\hat{\beta}_1 \hat{\beta}_2}$. Set $t: x \mapsto x' = a \cdot \frac{x - \alpha_2}{x - \alpha_1}, \ y \mapsto y' = \frac{y}{(x - \alpha_1)^3}$.

► How to compute $\sqrt{\hat{\beta}_1 \hat{\beta}_2}$? ► Why is it in *K*?

Division by 2 (Zarhin, 2016) Let $C: y^2 = g(x)$ with $g = c_g(x - r) \prod_{i=1}^4 (x - r_i)$ and P = (r, 0). Then any choice of square roots

$$\mathfrak{r} = (\mathfrak{r}_1, \dots, \mathfrak{r}_4) \in \bar{K}^4$$
 with $\mathfrak{r}_i^2 = r - r_i$ for $i \in \{1, 2, 3, 4\}$

defines a 4-torsion point $J(a_r, b_r) \in \mathcal{J}(\mathcal{C})$ with $2 \cdot J(a_r, b_r) = J(x - r, 0)$, where

$$a_{\mathfrak{r}} = (x-r)^2 - s_2(\mathfrak{r})(x-r) + s_4(\mathfrak{r}),$$
$$\frac{1}{\sqrt{c_g}} \cdot b_{\mathfrak{r}} = (s_1(\mathfrak{r})s_2(\mathfrak{r}) - s_3(\mathfrak{r}))(x-r) - s_1(\mathfrak{r})s_4(\mathfrak{r})$$

with s_i the *i*-th elementary symmetric polynomial in $\mathfrak{r} = (\mathfrak{r}_1, \ldots, \mathfrak{r}_4)$.

Computing $\sqrt{\beta_1\beta_2}$

Proposition (K.) Let $C: y^2 = c_f x(x - \beta_1)(x - \beta_2)(x - \gamma_1)(x - \gamma_2)$. If $R = J(x^2 + a_1 x + a_0, b_1 x + b_0) \in \mathcal{J}(\mathcal{C})(K)$ satisfies $2 \cdot R = J(x, 0)$, then

$$\sqrt{\beta_1 \beta_2} = \frac{(a_0 b_0 b_1 - a_1 b_0^2) \beta_1 \beta_2 + c_g a_0^2 (a_0 - \beta_1 \beta_2)^2}{b_0^2 \beta_1 \beta_2 + c_g a_0^2 (a_0 - \beta_1 \beta_2) (-a_1 - \beta_1 - \beta_2)}$$

Proof.

- Set r = 0 and $\mathfrak{r} = (\sqrt{-\beta_1}, \sqrt{-\beta_2}, \sqrt{-\gamma_1}, \sqrt{-\gamma_2}).$
- Extract $s_i(\mathfrak{r})$ from the Mumford coordinates of R.
- Use that $\mathfrak{r}_1\mathfrak{r}_2 = \frac{s_1(\mathfrak{r})s_3(\mathfrak{r})\mathfrak{r}_1^2\mathfrak{r}_2^2 + (s_4(\mathfrak{r}) \mathfrak{r}_1^2\mathfrak{r}_2^2)^2}{\mathfrak{r}_1^2\mathfrak{r}_2^2s_1(\mathfrak{r})^2 + (s_4(\mathfrak{r}) \mathfrak{r}_1^2\mathfrak{r}_2^2)(s_2(\mathfrak{r}) + \mathfrak{r}_1^2 + \mathfrak{r}_2^2)}.$

We compare our algorithm to other implementations on a typical G2SIDH instance with $\log(p)\approx 100$ and compute a $(2^{51},2^{51})$ -isogeny.

	pure isogeny	with image points
Genus-2 SIDH [FT '19]	72	127
SIDH-Attack [CD '22]	0.16	0.26
↓ sagemath [PO '22]	0.4	0.6
This work	0.06	0.08
$ \downarrow sagemath$	0.17	0.23

Table 1: Runtime in seconds on a laptop with Intel i7-8565U processor

Code and verification of all formulas:

https://github.com/sabrinakunzweiler/richelot-isogenies

Richelot Isogeny Chains on the Kummer Surface

Kummer Surface

For a genus-2 curve $C: y^2 = f(x)$, the Kummer surface is defined as $\mathcal{K}(\mathcal{C}) = \mathcal{J}(\mathcal{C})/\langle \pm 1 \rangle$.

- Quartic surface in \mathbb{P}^3 .
- 16 singular points corresponding to the 2-torsion points of $\mathcal{J}(\mathcal{C})$.
- Quotient map: $\xi : \mathcal{J}(\mathcal{C}) \to \mathcal{K}(\mathcal{C})$, $[(x_1, y_1) + (x_2, y_2) - D_{\infty}] \mapsto [1 : x_1 + x_2 : x_1 x_2 : \frac{\phi(x_1, x_2) - 2y_1 y_2}{(x_1 - x_2)^2}]$, where ϕ is a polynomial depending on f.

Example:

Let
$$C: y^2 = (x^2 - 1)(x^2 - A)(x^2 - Bx + C)$$
 be Type-2, then

• $\mathcal{K}(\mathcal{C}): (\xi_1^2 - 4\xi_0\xi_2) \cdot \xi_3^2 - 2((2C\xi_0 - B\xi_1 + 2E\xi_2)(-A\xi_0 + \xi_2)(-\xi_0 + \xi_2)) \cdot \xi_3 + \psi(\xi_0, \xi_1, \xi_2).$

•
$$\xi : J(x^2 - 1, 0) \mapsto [1 : 0 : -1 : (A + 1)(C - E)],$$

 $\xi : J(x^2 - A, 0) \mapsto [1 : 0 : -A : (A + 1)(C - AE)].$

Richelot Isogeny on the Kummer Surface

Proposition (K.) Let $C: y^2 = (x^2 - 1)(x^2 - A)(Ex^2 - Bx + C)$ with $B \neq 0$ and $G = \langle J(x^2 - 1, 0), J(x^2 - A, 0) \rangle \subset \mathcal{J}(\mathcal{C})[2].$

• Then
$$\mathcal{J}(\mathcal{C})/G = \mathcal{J}(\mathcal{C}')$$
 with
 $\mathcal{C}': y^2 = E'x(x^2 - A'x + 1)(x^2 - B'x + C')$ and
 $A' = 2\frac{E+C}{B}, B' = 2\frac{AE+C}{B}, C' = A, E' = 2B.$

• We provide explicit formulae for the induced map $\phi : \mathcal{K}(\mathcal{C}) \to \mathcal{K}(\mathcal{C}')$.

```
def KummerRichelot(coefficients, point):
    [A,B,C,E] = coefficients
    [x0,x1,x2,x3] = point
    y0 = (A*(E-C) - C)*x0^2 + C*x1^2 - B*x1*x2 + E*x2^2 + x0*x3
    y1 = A*B*x0^2 -2 (A*(C + E) + C)*x0*x1 + 2(A*E + C)*(C + E)/B*x1^2
    + B*(A + 1)*x0*x2 - 2*(A*E + C - E)*x1*x2 + B*x2^2 + x1*x3
    y2 = A*C*x0^2 - A*B*x0*x1 + A*E*x1^2 - (A*E - C + E)*x2^2 + x2*x3
    y3 = (A^2*(4*E^2 - B^2) - A*B^2)*x0^2 + A*B^2*x1^2 + 4*A*(2*C*E - A*B)*x0*x2
    - ((A + 1)*B^2 - 4*C^2)*x2^2 + 4*A*E*x0*x3 + 4*C*x2*x3 + x3^2
```

return [y0,y1,y2,y3]

Thank you!